

Dr. Joyanta Sarkar

RPM (Panchayat), B.A (TU), M.A (RBU), Ph.D (BITS Pilani), FMERU and FMERC (USA), DEC&E (Australia), CMCFD:F&A (NIT Jalandhar), CHR (Tripura University), Senior Diploma in Instrumental Music (Allahabad, India), Certificate Course on “Fishery Oceanography for Future Professionals” (Hyderabad, India)

Total No of National Patent= Published: 21 Nos, Granted: 07 Nos

Total No of International Patent= Published: 09 Nos, Granted: 01 Nos

Project Completed: 07.87 Cr. Under govt. of Japan/Australia/USA

Total No of National Award: 03 Nos

Total No of Research Paper: 17 Nos (Scopus Index, International)

Book Published: 01 Nos (Bharatiya Kala Prakashan, New Delhi, India)

Music Concerts: Rajarani Music Festival, Khairagarh Music Festival, etc



A Success Story of Panchayat Department, Govt. of Tripura

Sabki Yojana, Sabka Vikas



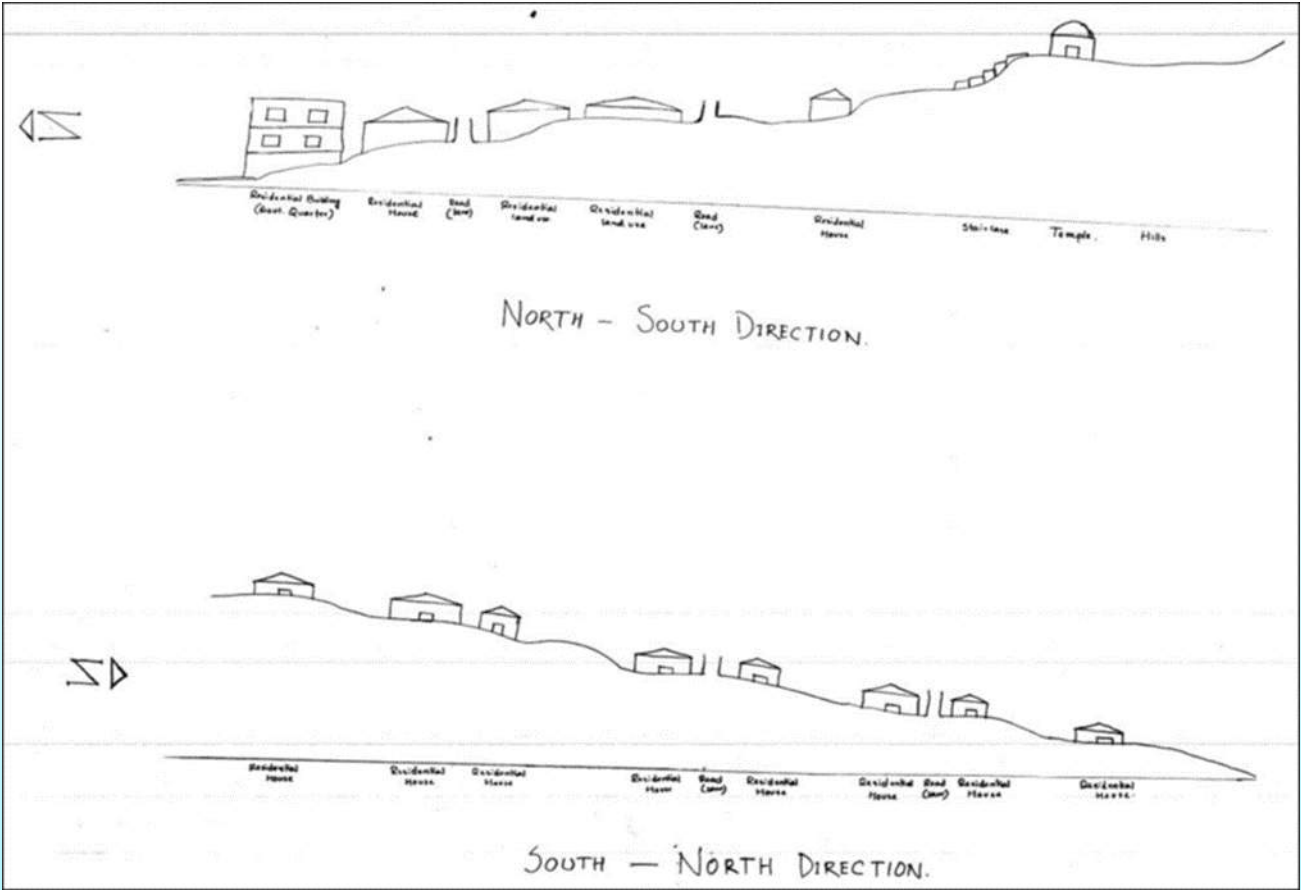
Sept 12, 2024

PARTICIPATORY RURAL APPRAISAL METHOD

- **Appraisal-** The finding out of information about problems, needs, and potential in a village. It is the first stage in any project
- **Participatory-** Means that people are involved in the process- a “bottom-up” approach that requires good communication skills and attitude of project staff
- **Rural-** The techniques can be used in any situation, Urban or Rural, with both literate and illiterate people



PARTICIPATORY RURAL APPRAISAL METHOD



PARTICIPATORY RURAL APPRAISAL METHOD



PARTICIPATORY RURAL APPRAISAL METHOD



PARTICIPATORY RURAL APPRAISAL METHOD



PARTICIPATORY RURAL APPRAISAL METHOD



PARTICIPATORY RURAL APPRAISAL METHOD



PARTICIPATORY RURAL APPRAISAL METHOD



PARTICIPATORY RURAL APPRAISAL METHOD



PARTICIPATORY RURAL APPRAISAL METHOD



PARTICIPATORY RURAL APPRAISAL METHOD



PARTICIPATORY RURAL APPRAISAL METHOD



PARTICIPANTS FEEDBACK

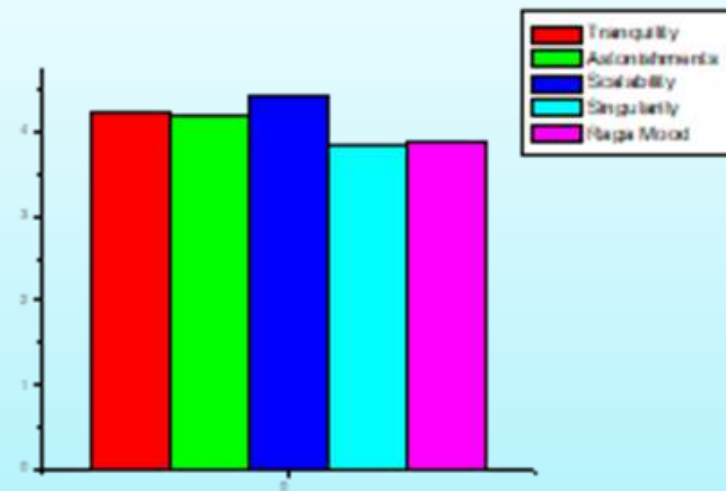
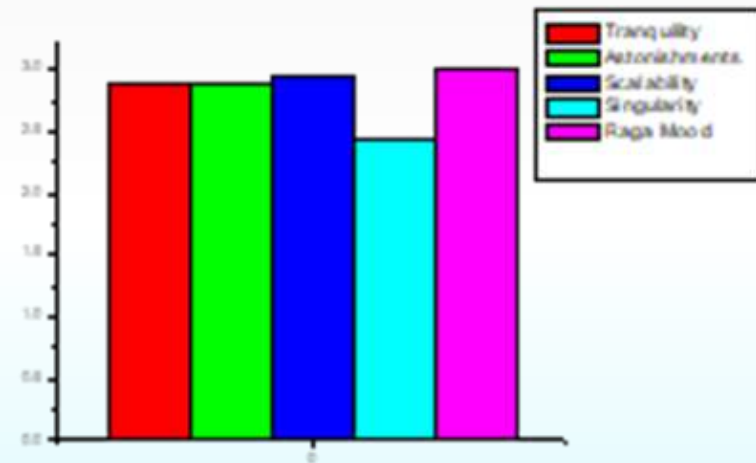
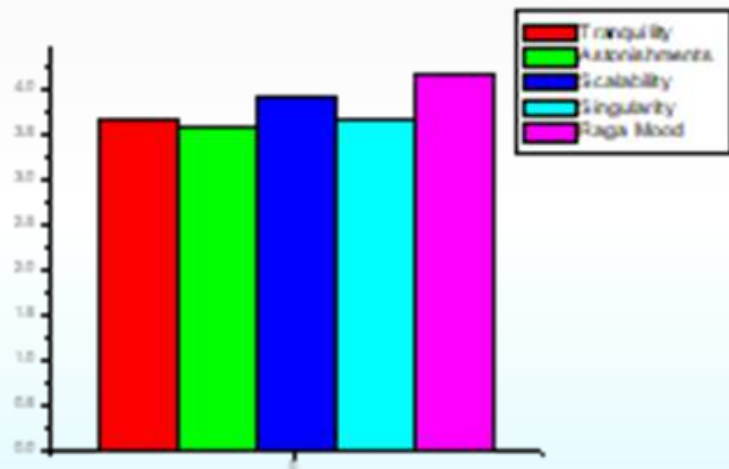
Participants	PRA Survey-TRIPURA				
	Ratings				
	Weak (1)	Modest (2)	Average (3)	Good (4)	Excellent (5)
27 Nos Participants					
25 Nos Participants					
17 Nos Participants					

	Ratings				
	Weak (1)	Modest (2)	Average (3)	Good (4)	Excellent (5)
29 Nos Participants					
21 Nos Participants					
19 Nos Participants					

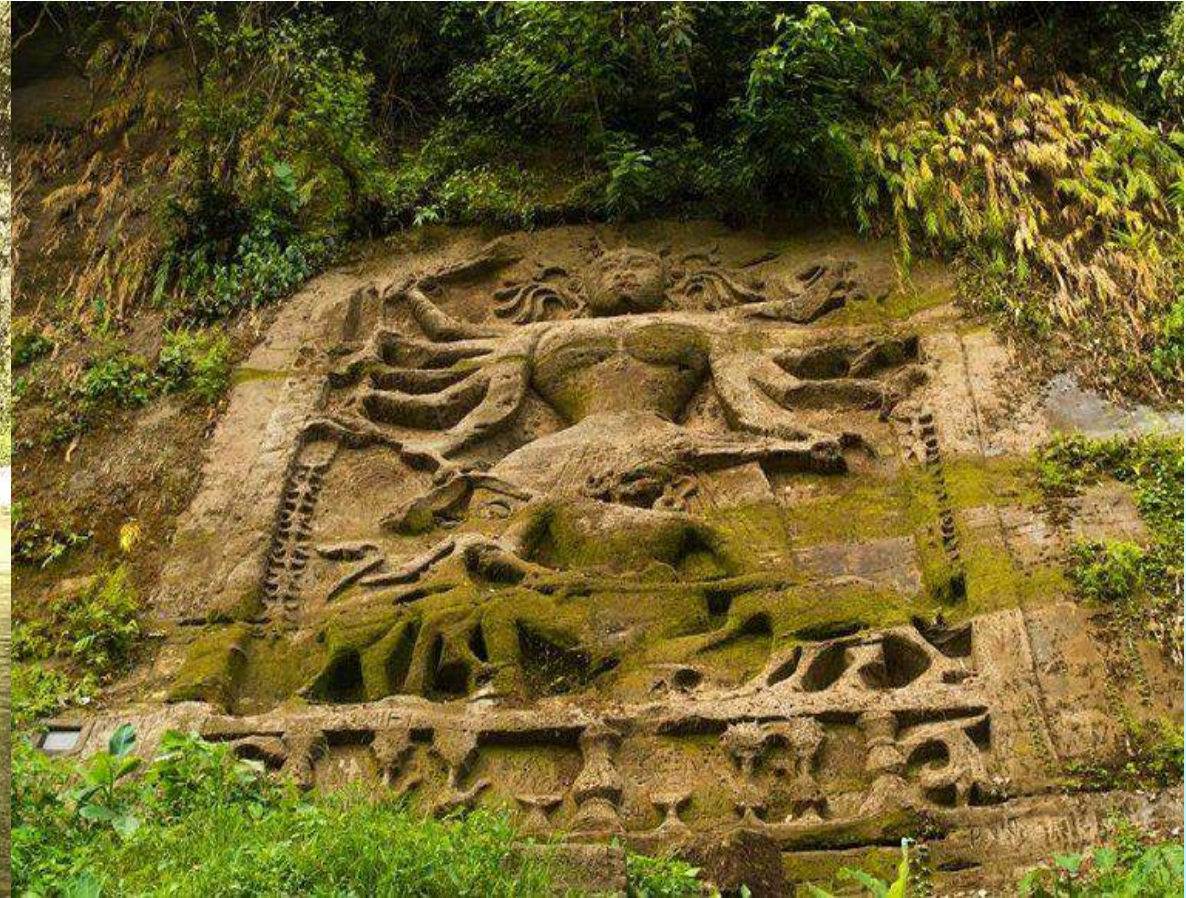
	Ratings				
	Weak (1)	Modest (2)	Average (3)	Good (4)	Excellent (5)
27 Nos Participants					
29 Nos Participants					
13 Nos Participants					

Participant Interest

RESULTS



CHABIMURA



BAMBOO SPECIES AVAILABLE IN CHABIMURA

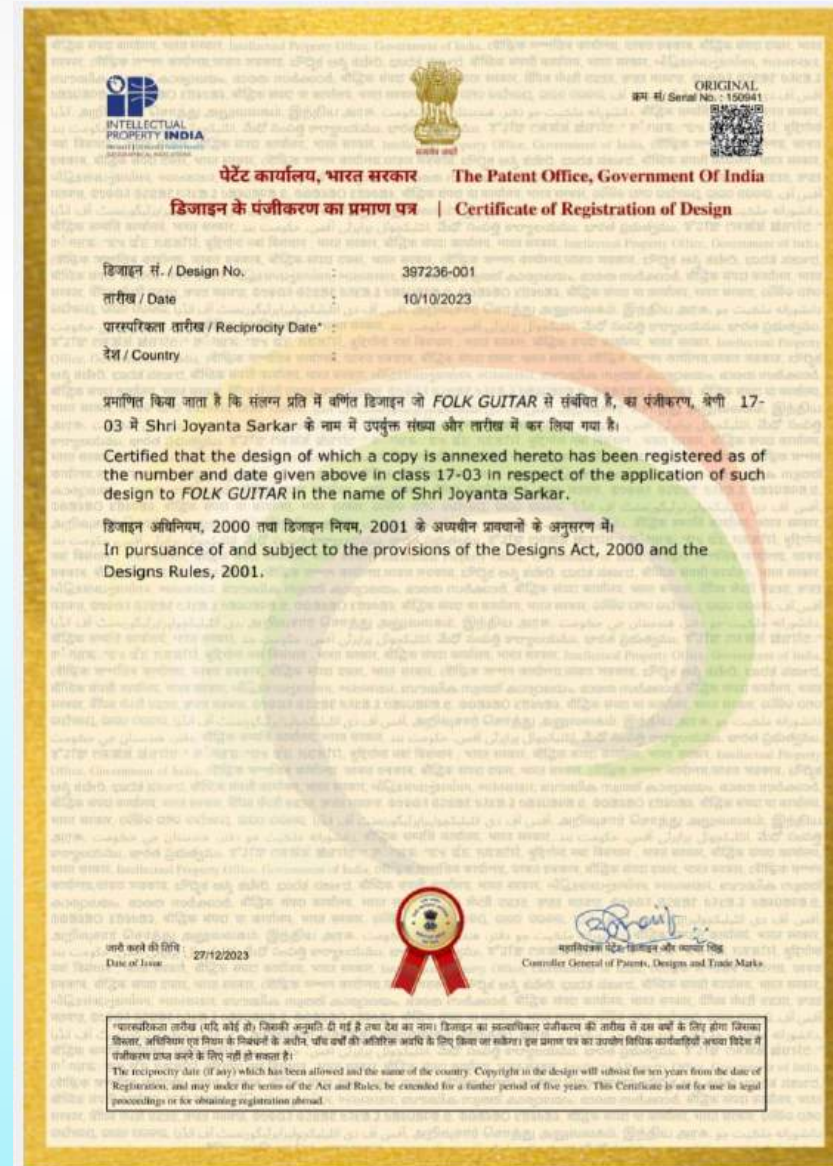
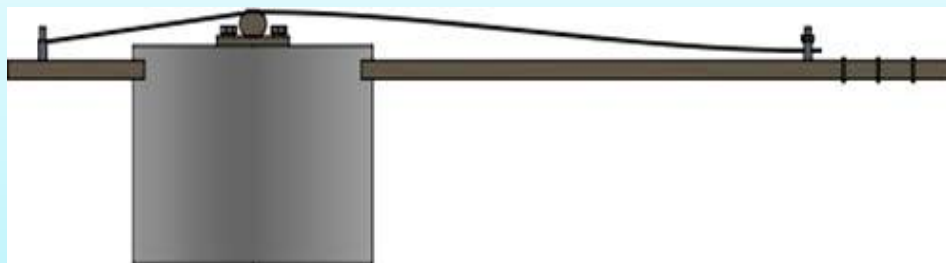
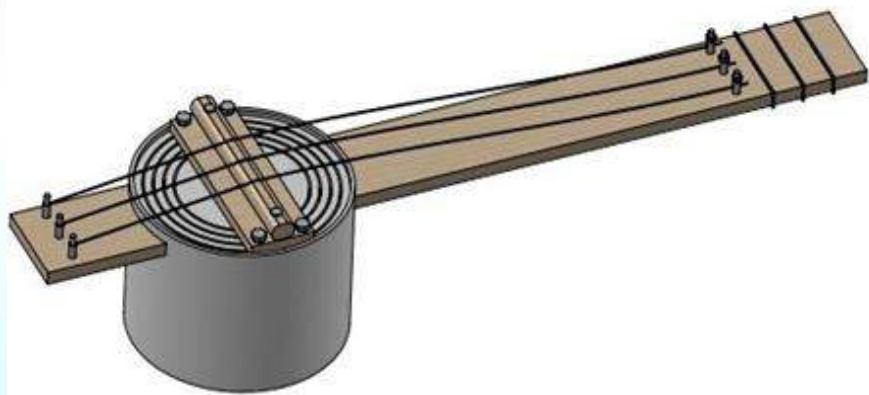
11 species of bamboos are found in Chabimura. Most common bamboos are;

- Muli (*Melocanna baccifera*),
- Barak (*Bambusa balcooa*),
- Bari (*Bambusa polymorpha*),
- Mritinga (*Bambusa tulda*),
- Paora (*Bambusa teres*),
- Rupai (*Dendrocalamus longispathus*),
- Dolu (*Neohuzeaua dullooa*),
- Makal (*Bambusa pallida*),
- Pecha (*Dendrocalamus hamiltonii*),
- Kanak kaich (*Bambusa affinis*),
- Jai (*Bambusa* spp.)



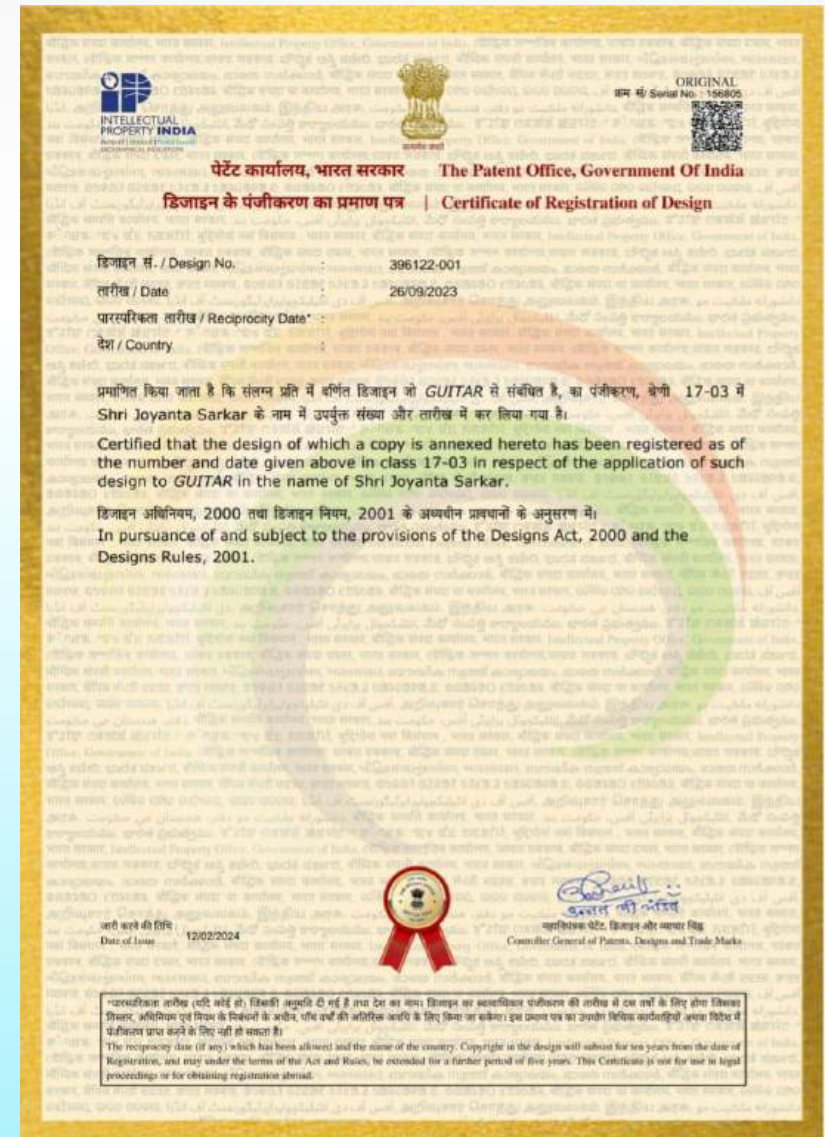
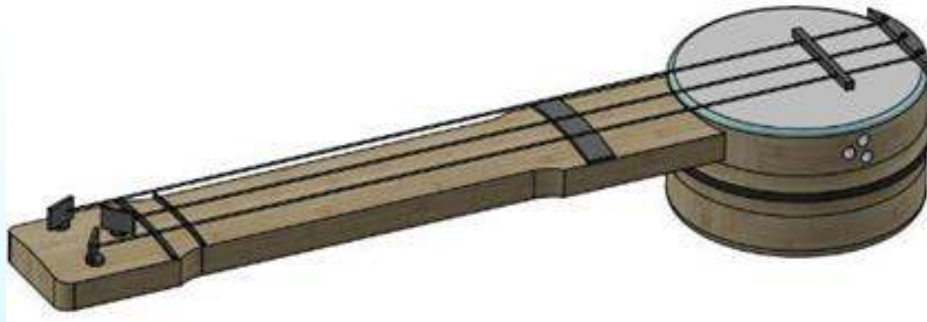
Patent

➤ Tripuri Folk Guitar



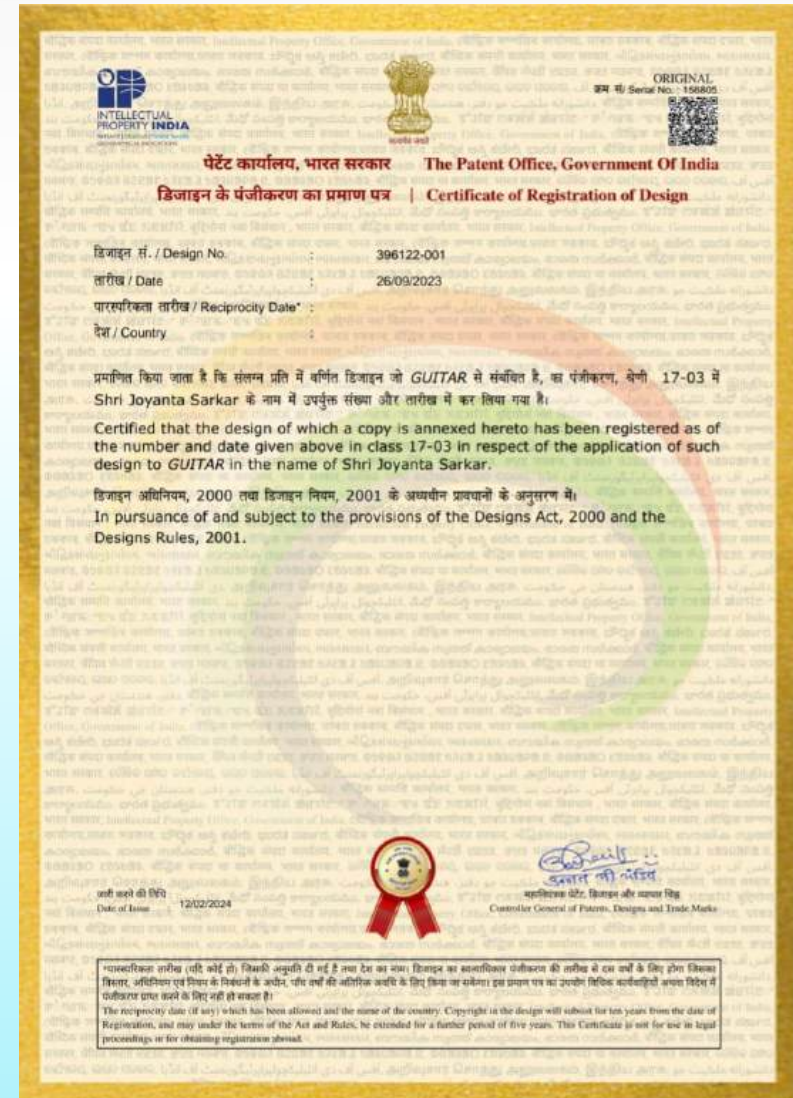
Patent

➤ Tipara Guitar



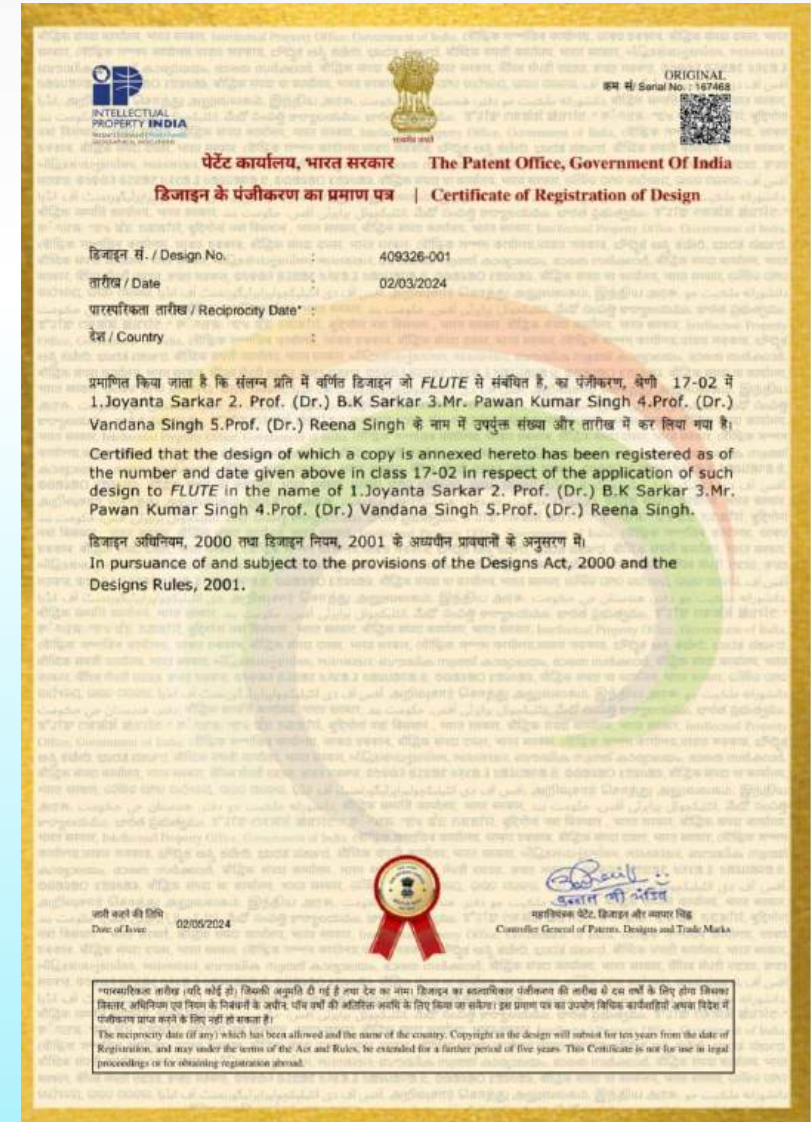
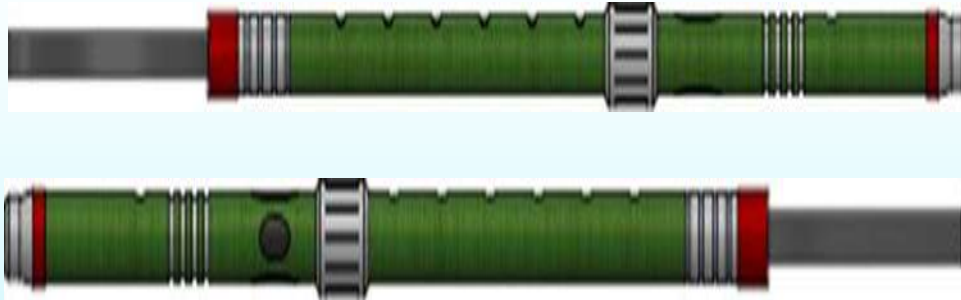
Patent

➤ Gourd based Guitar



Patent

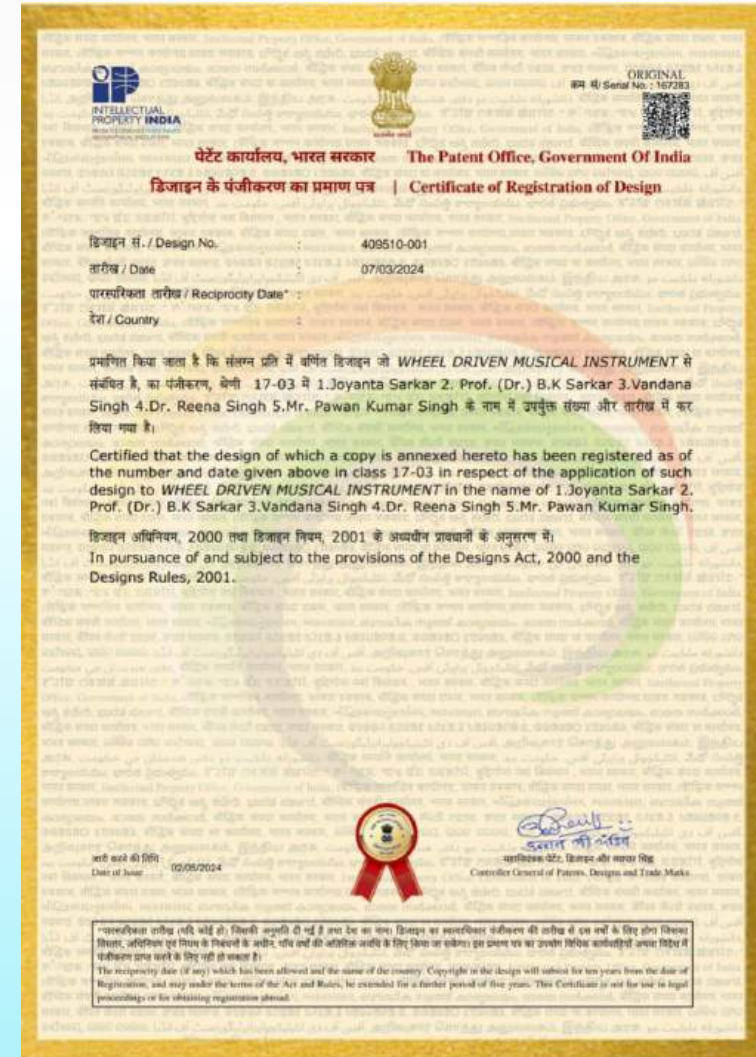
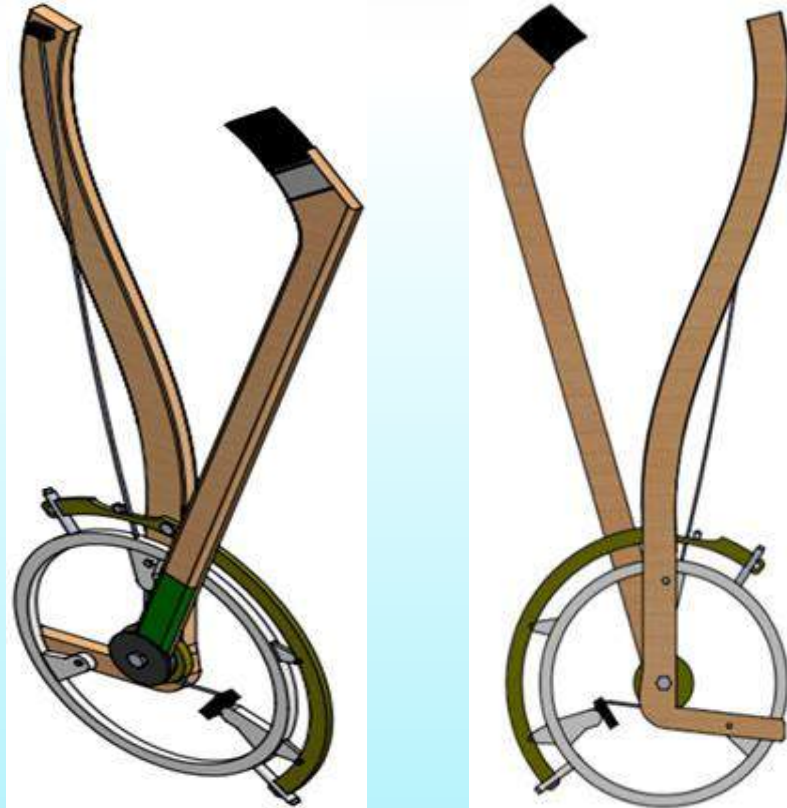
➤ Makal Flute



*पारस्परिकता तारीख (यदि कोई हो) जिसकी अनुमति दी गई है तथा देश का नाम। डिजाइन का स्वतंत्रिकार पंजीकरण की तारीख से दस वर्षों के लिए होता है।
निसर, अधिनियम एवं नियम के निवचनों के अंतर्गत, पाँच वर्षों की अवधि के लिए किया जा सकता है। इस प्रमाण पत्र का उपयोग विवाद सार्वजनिक अथवा विदेश में
पंजीकरण प्राप्त करने के लिए नहीं हो सकता है।
The reciprocity date (if any) which has been allowed and the name of the country. Copyright in the design will subsist for ten years from the date of
Registration, and may under the terms of the Act and Rules, be extended for a further period of five years. This Certificate is not for use in legal
proceedings or for obtaining registration abroad.

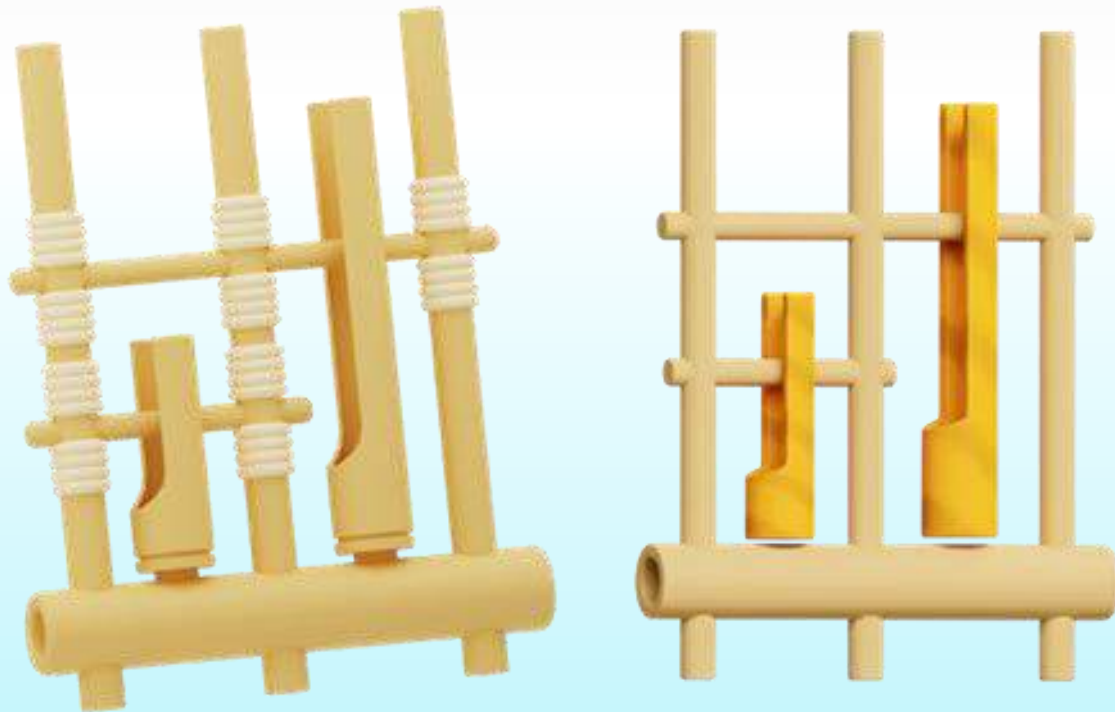
Patent

➤ Wheel Driven Musical Instrument



Patent

➤ Bamboo Based Guitar



Certificate of Registration for a UK Design

Design number: 6349227

Grant date: 11 March 2024

Registration date: 26 February 2024

This is to certify that,

in pursuance of and subject to the provision of Registered Designs Act 1949, the design of which a representation or specimen is attached, had been registered as of the date of registration shown above in the name of

Joyanta Sarkar, Prof. (Dr.) Biplab Kumar Sarkar, Mr. Pawan Kumar Singh, Prof.

(Dr.) Vandana Singh, Prof. (Dr.) Reena Singh

in respect of the application of such design to:

Stringed musical instrument

International Design Classification:

Version: 14-2023

Class: 17 MUSICAL INSTRUMENTS

Subclass: 03 STRINGED INSTRUMENTS

Adam Williams

Adam Williams
Comptroller-General of Patents, Designs and Trade Marks
Intellectual Property Office

The attention of the Proprietor(s) is drawn to the important notes overleaf.



Intellectual Property Office is an operating name of the Patent Office

www.gov.uk/ipoo

Patent

- Kalyanmoy Deb is an Indian [Computer scientist](#). Deb is the Herman E. & Ruth J. Koenig Endowed Chair Professor in the Department of Electrical and Computing Engineering at [Michigan State University](#). Deb is also a professor in the Department of Computer Science and Engineering and the Department of Mechanical Engineering at [Michigan State University](#).



NSGA II OPTIMIZATION

$$S(R) = \frac{\sum_{u=1}^k (T_j^{end} - T_j^{start}) \beta(r_j = r)}{D_z \beta(r_j = r)} \dots\dots\dots (1)$$

$$I(Int) = \sum_{j=1}^l \frac{(T_j^{end} - T_j^{start}) \beta(I_{R_j} = I)}{S(R_j)} \dots\dots\dots (2)$$

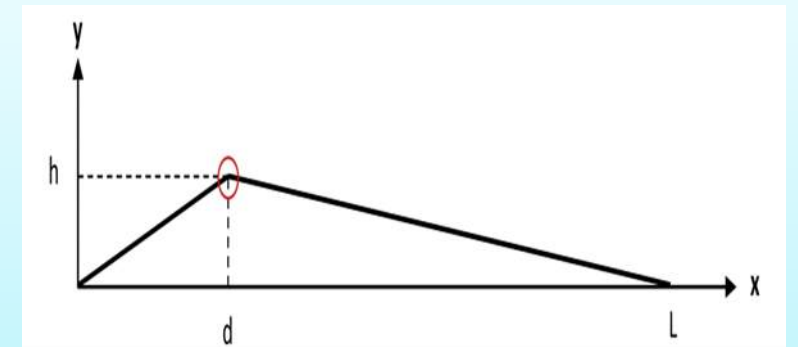
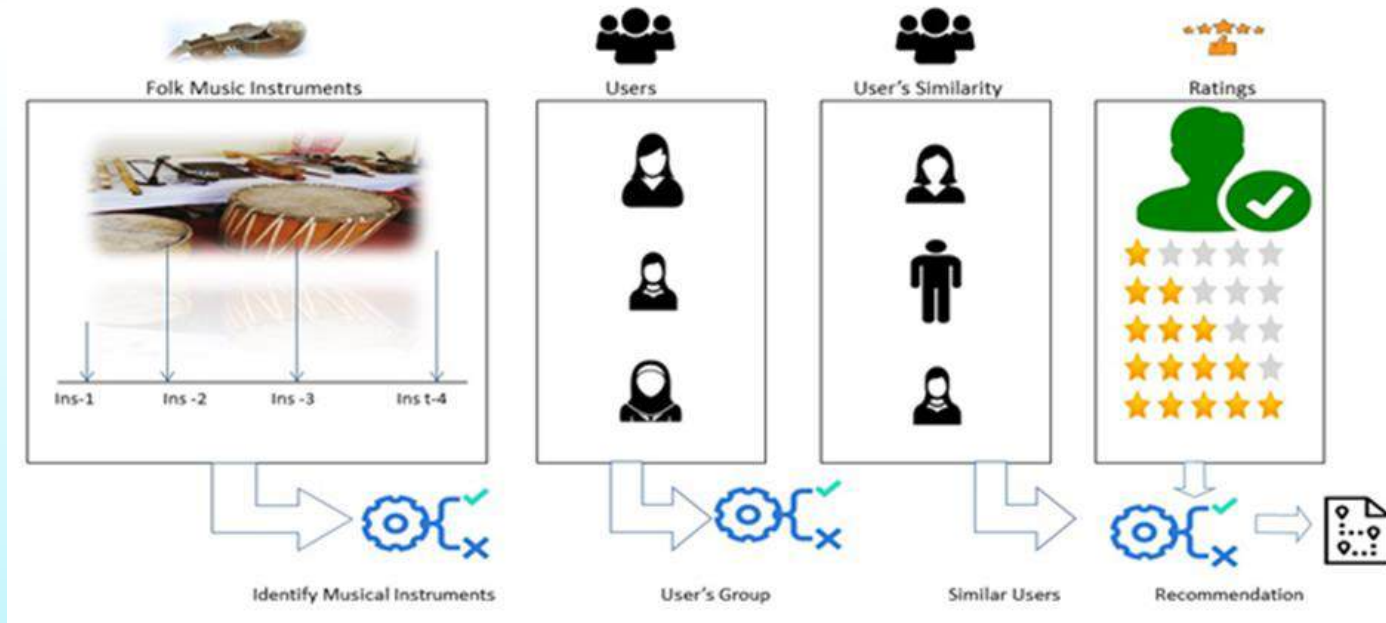
$$U(I) = \sum_{u=1}^l \sum_{r=1}^k (T_j^{end} - T_j^{start}) \beta(I_j = I) \dots\dots\dots (3)$$

$$\text{Cos}(U_x, U_y) = \frac{I(Int)_{U_x} \cdot I(Int)_{U_y}}{\|I(Int)_{U_x}\| \cdot \|I(Int)_{U_x}\|} \dots\dots\dots (4)$$

$$\frac{\text{Max}(\pi U_{Int} + (1 - \pi) U_{pop})}{\text{Cost}(I)} \dots\dots\dots (5)$$

NSGA II OPTIMIZATION

NSGA II optimization technic in our work To solve the multi objective problems



WHAT IS NSGA II OPTIMIZATION TECHNIC

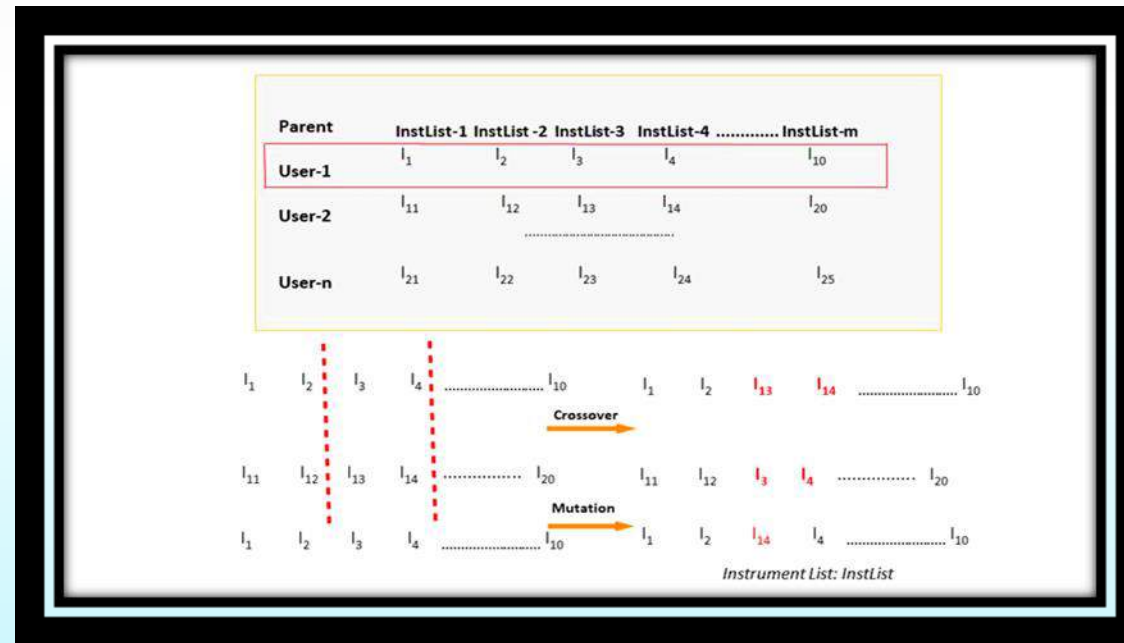


Fig: Crossover and Mutation Process

METHODOLOGY

The overall structure of the one-dimensional wave mathematical claim, where the fixed endpoints are to be:

$$y(x, t) = \sum_i X_i(x)T_i(t) = \sum_{k=1}^{\infty} \sin\left(\frac{k\pi}{L}x\right) \left(\alpha_k \cos\left(\frac{ck\pi}{L}t\right) + \beta_k \sin\left(\frac{ck\pi}{L}t\right)\right) \dots\dots\dots(1)$$

Where,

$$c = \sqrt{(T/\mu)}$$

The natural frequencies are $ck\pi/L$

METHODOLOGY

Using 1, gives

$$\begin{aligned} f(x) = y(x, 0) &= \sum_{k=1}^{\infty} \sin\left(\frac{k\pi}{L}x\right) \left(\alpha_k \cos\left(\frac{ck\pi}{L} \times 0\right) + \beta_k \sin\left(\frac{ck\pi}{L} \times 0\right)\right) \\ &= \sum_{k=1}^{\infty} \alpha_k \sin\left(\frac{k\pi}{L}x\right) \end{aligned} \dots\dots\dots(2)$$

$$\frac{\partial}{\partial t} y(x, 0) = \frac{\partial}{\partial t} \sum_{k=1}^{\infty} \sin\left(\frac{k\pi}{L}x\right) \left(\alpha_k \cos\left(\frac{ck\pi}{L}t\right) + \beta_k \sin\left(\frac{ck\pi}{L}t\right)\right)$$

$$= \sum_{k=1}^{\infty} \sin\left(\frac{k\pi}{L}x\right) \left(\alpha_k \frac{\partial}{\partial t} \cos\left(\frac{ck\pi}{L}t\right) + \beta_k \frac{\partial}{\partial t} \sin\left(\frac{ck\pi}{L}t\right)\right) \dots\dots\dots(3)$$

Applying derivatives to the chain rule:

$$\frac{\partial}{\partial t} \cos\left(\frac{ck\pi}{L}t\right) = -\left(\frac{ck\pi}{L}\right) \sin\left(\frac{ck\pi}{L}t\right) \dots\dots\dots(4)$$

$$\frac{\partial}{\partial t} \sin\left(\frac{ck\pi}{L}t\right) = \left(\frac{ck\pi}{L}\right) \cos\left(\frac{ck\pi}{L}t\right)$$

METHODOLOGY

Applying NSGA II Optimization, Part 1:

$$A_k = \frac{2}{L} \int_0^L f(x) \sin\left(\frac{k\pi x}{L}\right) dx = \frac{2}{L} \left[\underbrace{\int_0^d \frac{hx}{d} \sin\left(\frac{k\pi x}{L}\right) dx}_{\text{Part 1}} + \underbrace{\int_d^L \frac{h(L-x)}{L-d} \sin\left(\frac{k\pi x}{L}\right) dx}_{\text{Part 2}} \right]$$

Setting $u = \frac{hx}{d}$ and $dv = \sin\left(\frac{k\pi x}{L}\right) dx$

$$\begin{aligned} \int_0^d \frac{hx}{d} \sin\left(\frac{k\pi x}{L}\right) dx &= \left[\frac{hx}{d} \left(\frac{-L}{k\pi}\right) \cos\left(\frac{k\pi x}{L}\right) \right]_0^d - \int_0^d \left(\frac{-L}{k\pi}\right) \cos\left(\frac{k\pi x}{L}\right) \frac{h}{d} dx \\ &= \left[\frac{-hLx}{k\pi d} \cos\left(\frac{k\pi x}{L}\right) \right]_0^d - \int_0^d \frac{-hL}{k\pi d} \cos\left(\frac{k\pi x}{L}\right) dx \\ &= \left[\frac{-hLx}{k\pi d} \cos\left(\frac{k\pi x}{L}\right) \right]_0^d - \left(\frac{-hL}{k\pi d}\right) \left[\frac{L}{k\pi} \sin\left(\frac{k\pi x}{L}\right) \right]_0^d \\ &= \frac{-hLd}{k\pi d} \cos\left(\frac{k\pi d}{L}\right) - \left(\frac{-hL \times 0}{k\pi d}\right) \cos\left(\frac{k\pi \times 0}{L}\right) \\ &\quad + \frac{hL}{k\pi d} \frac{L}{k\pi} \left(\sin\left(\frac{k\pi d}{L}\right) - \sin\left(\frac{k\pi \times 0}{L}\right) \right) \\ &= \frac{-hL}{k\pi} \cos\left(\frac{k\pi d}{L}\right) + \frac{hL^2}{k^2\pi^2 d} \sin\left(\frac{k\pi d}{L}\right) \end{aligned}$$

METHODOLOGY

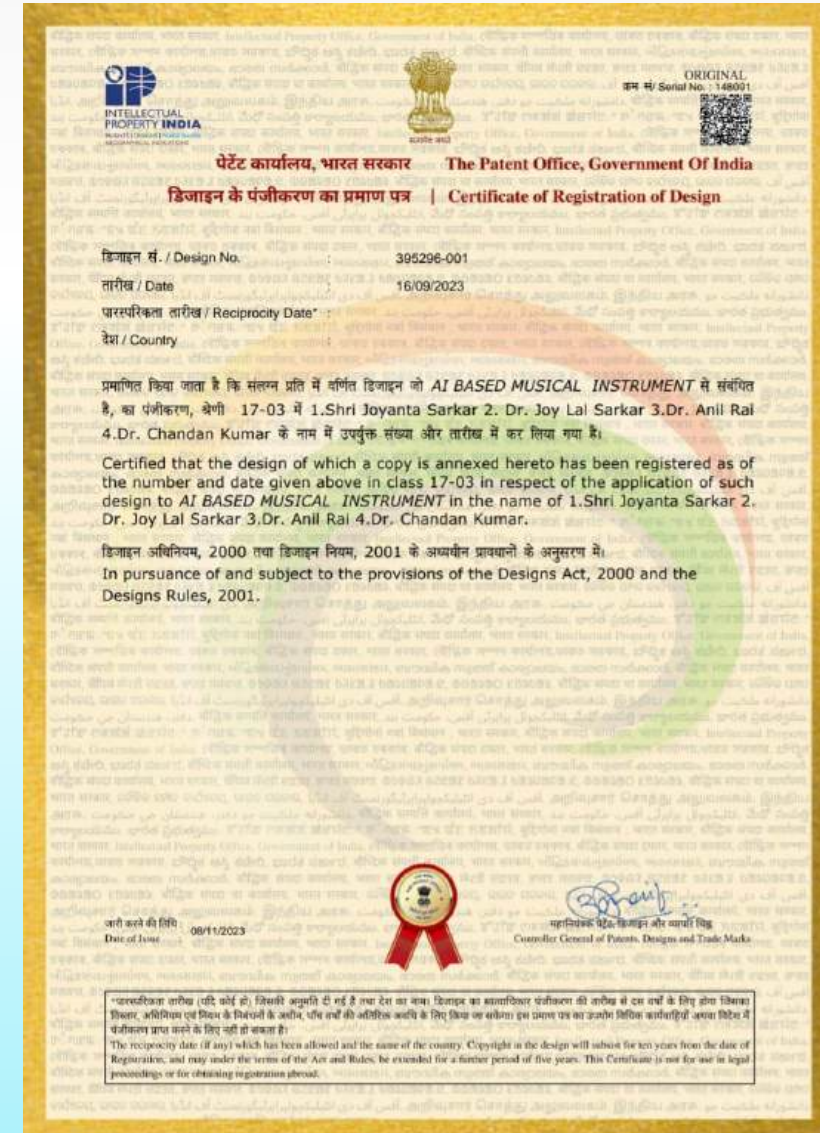
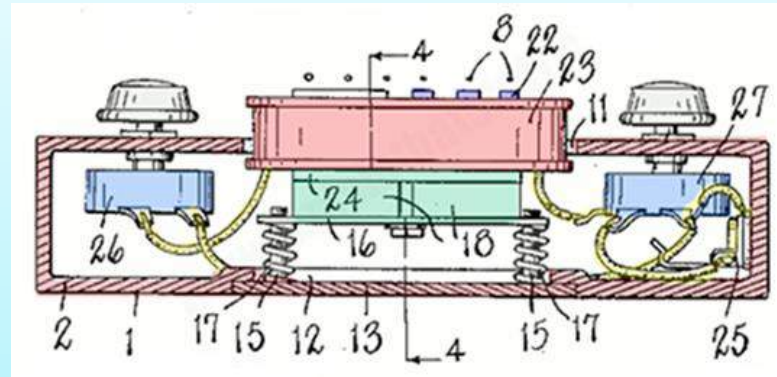
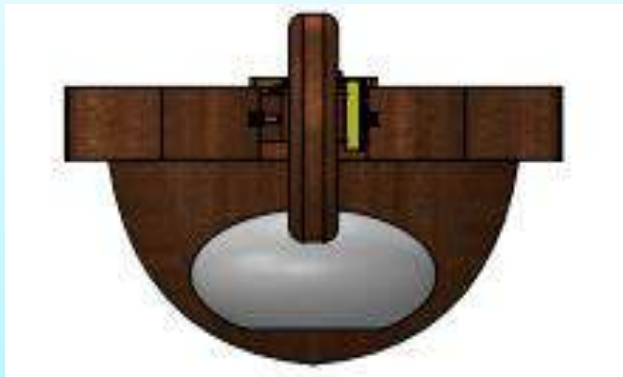
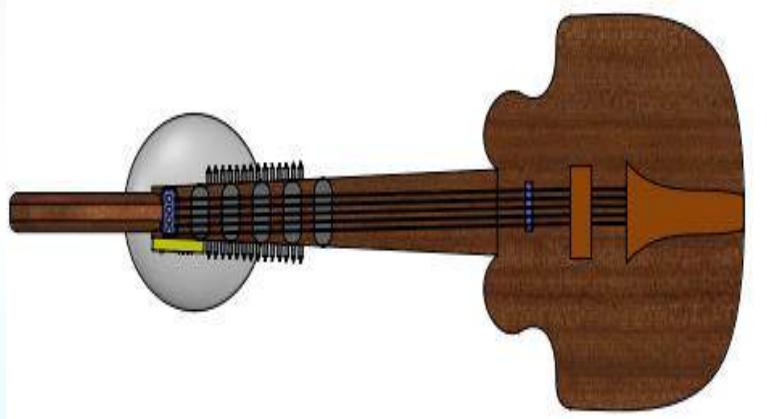
Applying NSGA II Optimization, Part 2:

Setting $u = \frac{h(L-x)}{L-d}$ and $dv = \sin\left(\frac{k\pi x}{L}\right) dx$

$$\begin{aligned}\int_d^L \frac{h(L-x)}{L-d} \sin\left(\frac{k\pi x}{L}\right) dx &= \left[\frac{h(L-x)}{L-d} \left(\frac{-L}{k\pi}\right) \cos\left(\frac{k\pi x}{L}\right) \right]_d^L - \int_d^L \left(\frac{-L}{k\pi}\right) \cos\left(\frac{k\pi x}{L}\right) \frac{-h}{L-d} dx \\ &= \left[\frac{-h(L-x)L}{(L-d)k\pi} \cos\left(\frac{k\pi x}{L}\right) \right]_d^L - \int_d^L \frac{hL}{(L-d)k\pi} \cos\left(\frac{k\pi x}{L}\right) dx \\ &= \left[\frac{-h(L-x)L}{(L-d)k\pi} \cos\left(\frac{k\pi x}{L}\right) \right]_d^L - \frac{hL}{(L-d)k\pi} \left[\frac{L}{k\pi} \sin\left(\frac{k\pi x}{L}\right) \right]_d^L \\ &= \frac{-h(L-L)L}{(L-d)k\pi} \cos\left(\frac{k\pi L}{L}\right) - \frac{h(L-d)L}{(L-d)k\pi} \cos\left(\frac{k\pi d}{L}\right) \\ &\quad - \frac{hL}{(L-d)k\pi} \frac{L}{k\pi} \left(\sin\left(\frac{k\pi L}{L}\right) - \sin\left(\frac{k\pi d}{L}\right) \right) \\ &= \frac{hL}{k\pi} \cos\left(\frac{k\pi d}{L}\right) + \frac{hL^2}{(L-d)k^2\pi^2} \sin\left(\frac{k\pi d}{L}\right)\end{aligned}$$

Patent

➤ Artificial Intelligence (AI) based Musical Instrument



Patent

➤ Leaf Flute



Patent

➤ **Bamboo based musical instrument**



Patent

➤ Wind Musical Instrument



THANK YOU